

Bestic

bestic.se

General Description

Bestic can be described as a robotic arm with a spoon or pincers at the end. The user controls the movements by means of buttons, joystick or other controls to select food from the plate and move it to the mouth. The user is thus able to eat without external help.

Bestic is designed to suit a laid table.

It operates from the mains but has a battery with sufficient capacity for a long meal. This makes it easier for the user to bring Bestic along to a restaurant, to friends or to places without electricity.

Operating mode

Bestic moves the spoon to the plate and fetches the food that the user chooses. It lifts the food to mouth height and stops. The user leans forward and takes the food, then gives a signal to Bestic to repeat the operation.

Fetching modes

- Semi automatic: The spoon moves over the plate in lines, waiting for the user to give a signal to fetch food from current position. In this mode, Bestic can be controlled with only one button or signal possibility.
- Manual: The spoon is controlled freely over the plate by the user with either buttons or with a joystick. It then picks food from chosen position, when the user gives a signal.

Technical information

Bestic is designed to be controlled by different controls available on the market. Bestic is adapted to the user and to the controls the user is familiar with.

Inputs

- Digital (6)
- Analogue (2)
- RS-232 (via wire or built in IR)

Weight

Less than 2.5 kg (including battery, IR-receiver and charger)

Size

Transport mode: height: 34 cm, width: 22 cm, depth: 20 cm

Operating time on battery

more than 1 hour

